

# Algorithm and Demonstration of Fringe Fitting for DOR Tones in Geodetic VLBI

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First International Workshop on VLBI Observations of Near-field Targets

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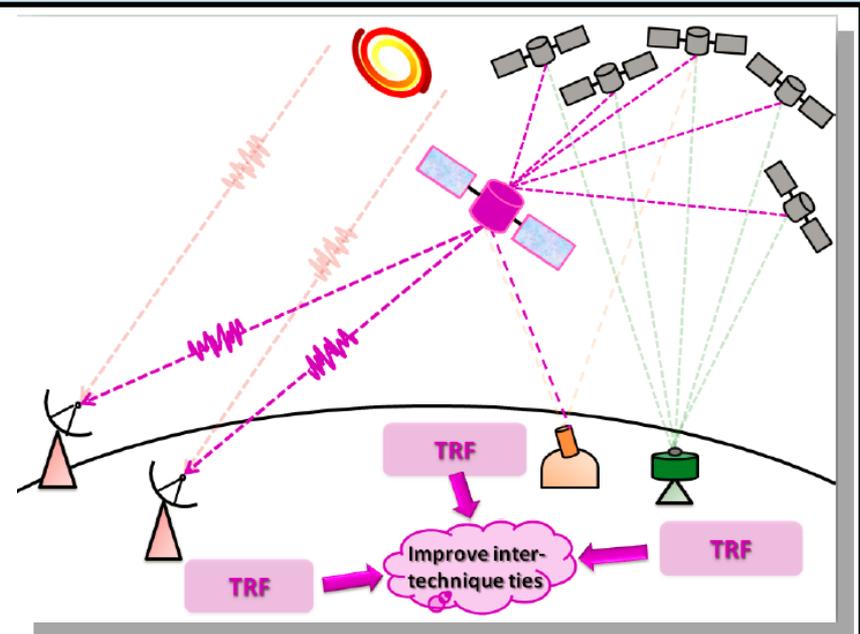
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1. Introduction
2. Algorithm and Analysis
3. Experiment and Comparison
4. Summary

- Geodetic VLBI has been used to improve the frame ties between ICRF realized with VLBI observations of extragalactic quasar and spacecraft orbits realizing celestial frames. (Haas 2014; <http://vlbi.geo.tuwien.ac.at/sorts/abstract/>)



Plank, 2014

- DOR (Differential One-way Ranging) tone transponder is usually deployed by spacecraft for high accuracy interferometric tracking. (CCSDS; Border, 2015)
- **DOR Tones narrow spectrum is totally different from quasar continuum spectrum.**

- Interferometric phase output by FX type correlator can be expressed through first-order expansion. (Reynolds,2007)

$$\Delta\phi_{t,v} = \phi_0 + \frac{\partial\phi}{\partial v}\Delta v + \frac{\partial\phi}{\partial t}\Delta t$$

delay     rate

- Processing that estimates the delay and rate residuals is referred to as fringe fitting.

## fringe-fitting in *fourfit*

- 2 steps
  - coarse grid search
  - refinement of parameter estimates
- grid search done via FFT's:
  - over frequency to find delay
  - over time to find fringe/delay rate
  - over "lag" to find single-band delay

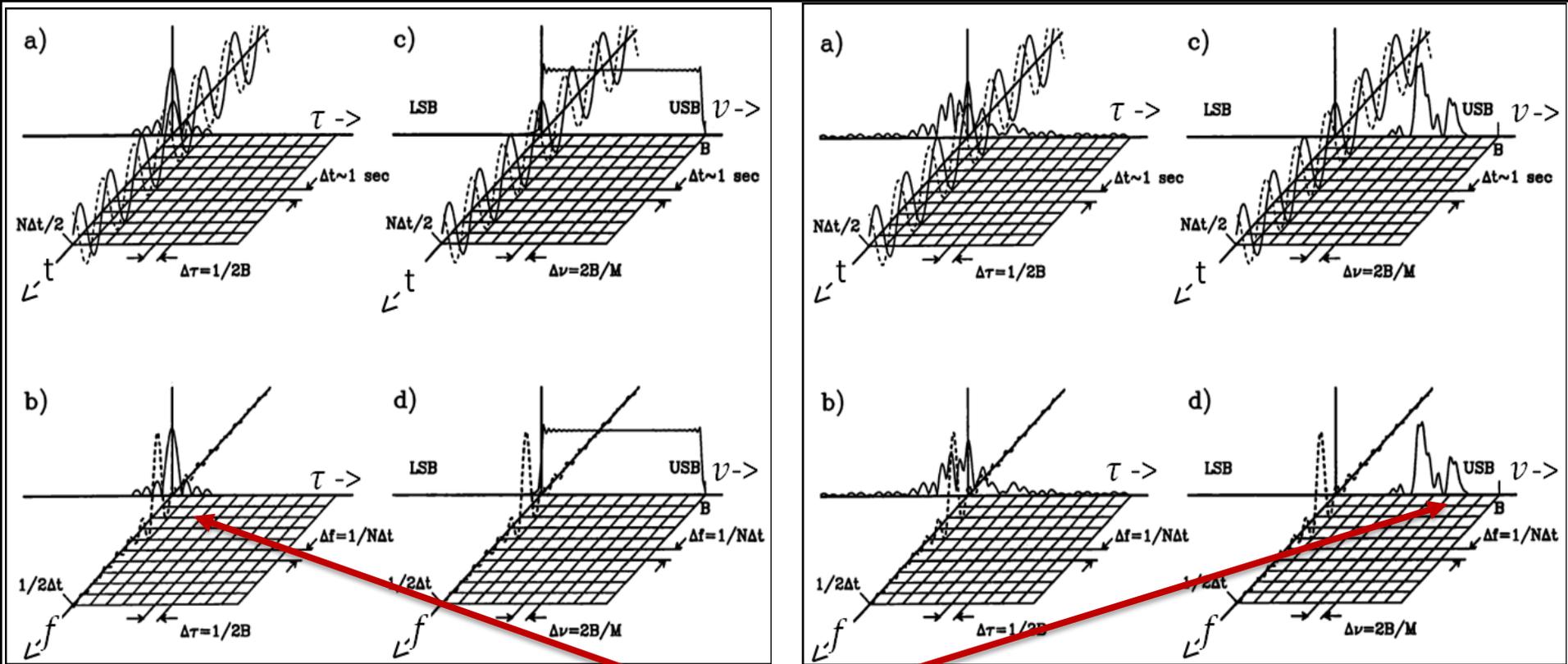
- refinement
  - counter-rotate data and coherently sum:

$$\mathbf{g}(\tau, \dot{\tau}) = \sum_f \sum_t \mathbf{V}(f, t) e^{-2\pi i(f\dot{\tau}t + f\tau + \delta\phi)}$$

- interpolate from closely-spaced grid-points

- Analysis in the domain of "**delay – fringe rate**" through Fourier Transform;
- 3-D search  
(Single Band Delay  
Multi Band Delay  
fringe-rate)

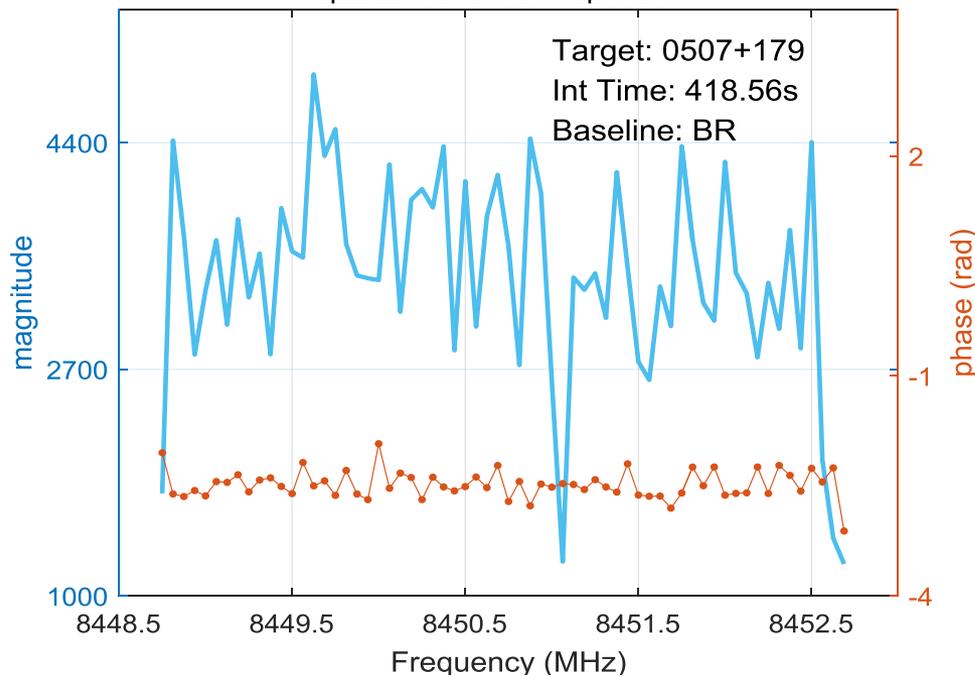
(Cappallo, IVS VLBI School, 2016)



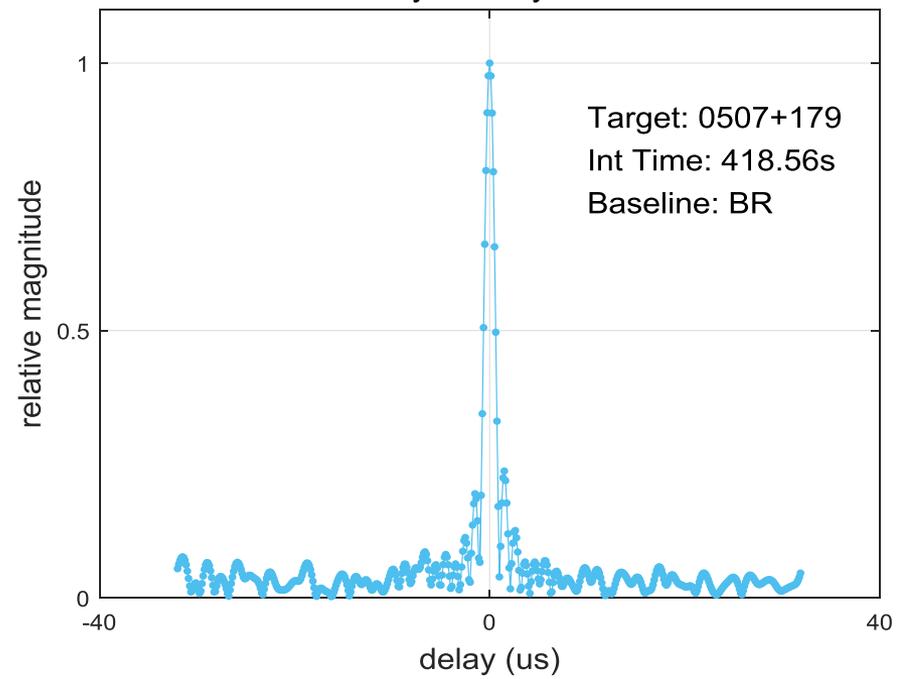
(Reid, 1995)

visibility amplitude peaks sharply in both axis and most easily detected.

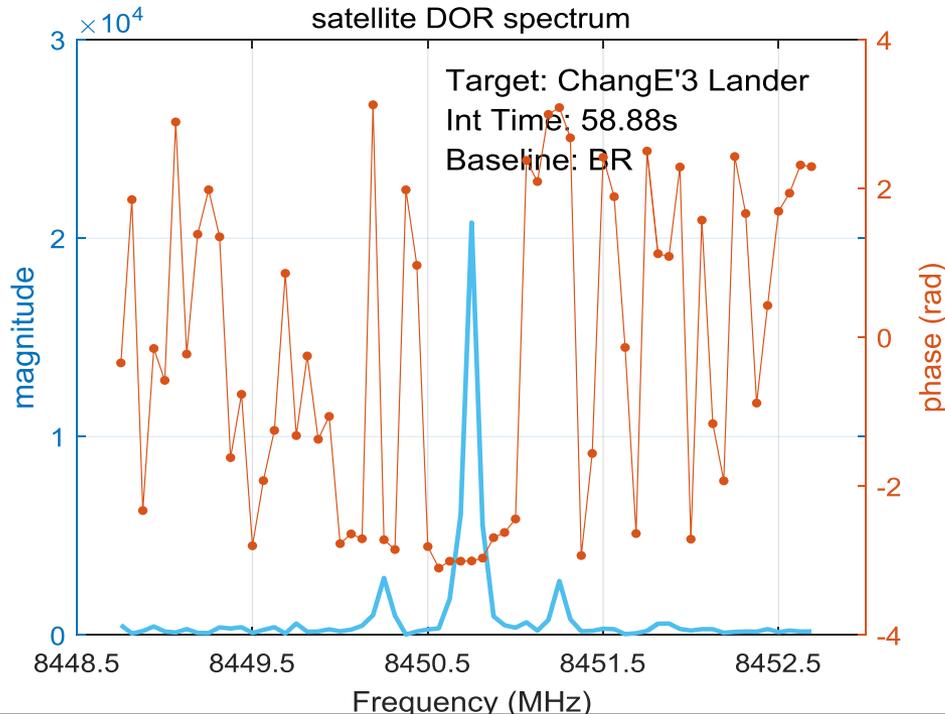
quasar continuum spectrum



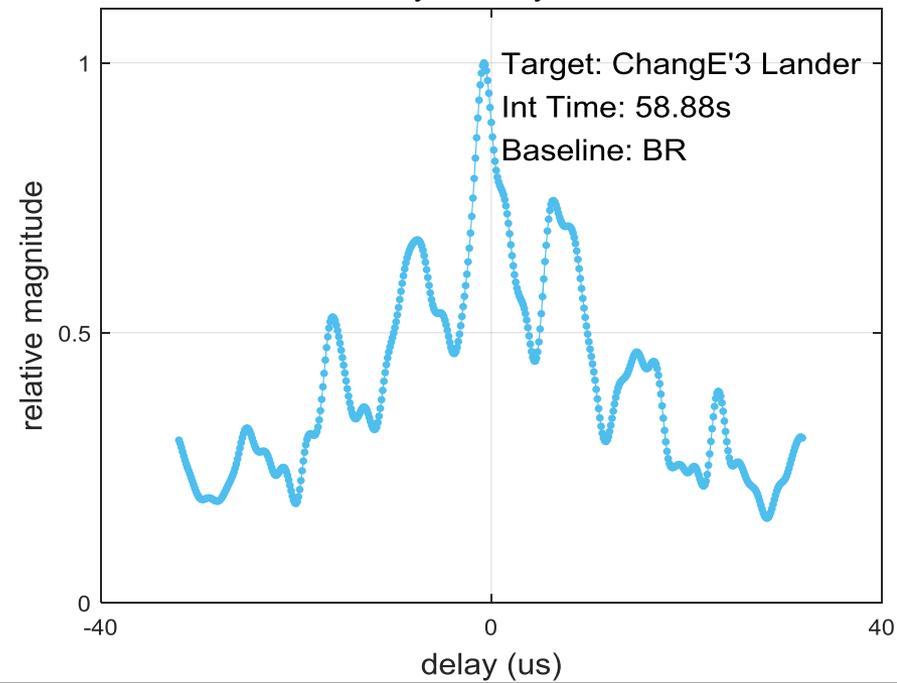
visibility in delay domain

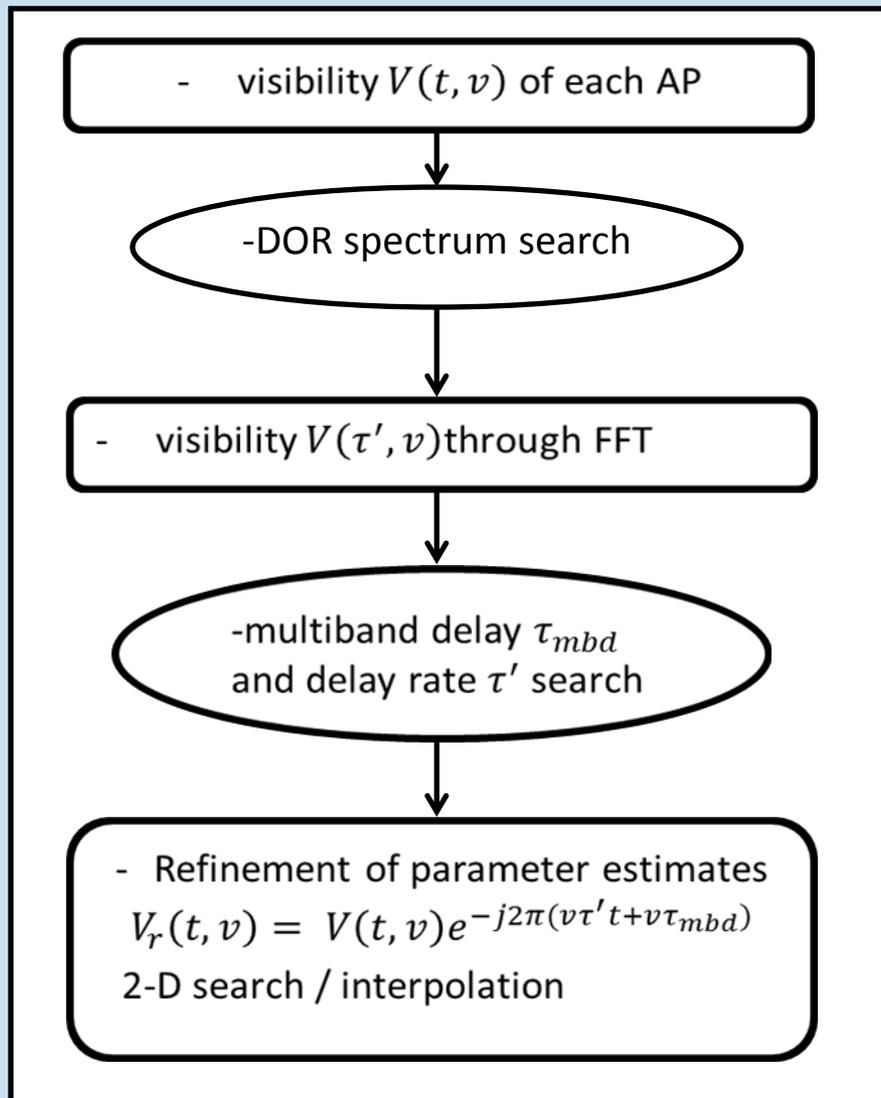


satellite DOR spectrum



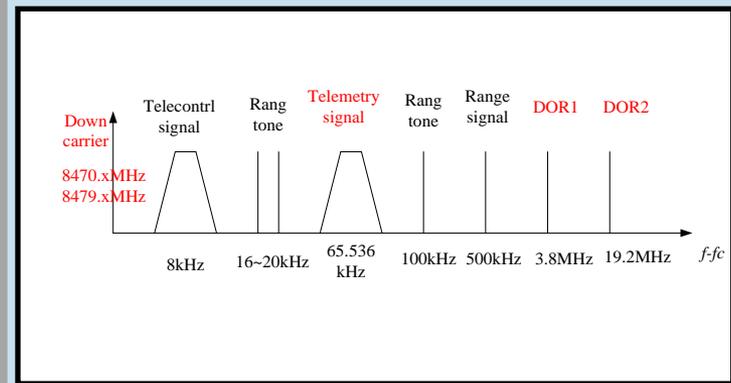
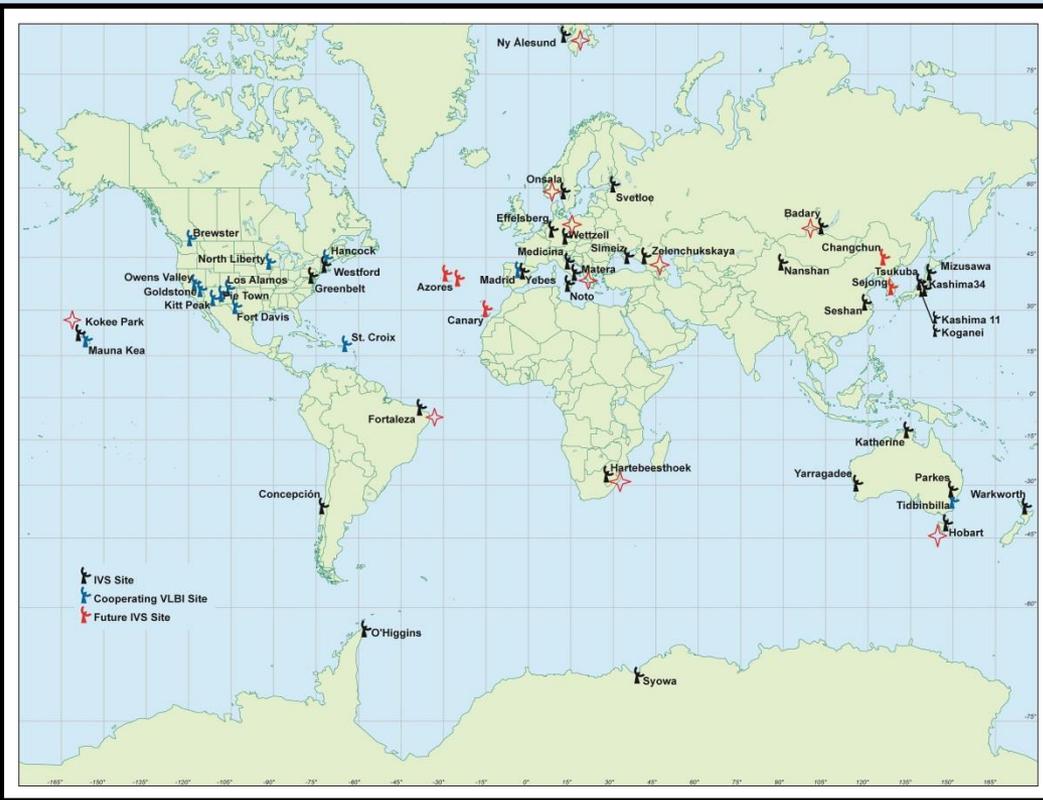
visibility in delay domain





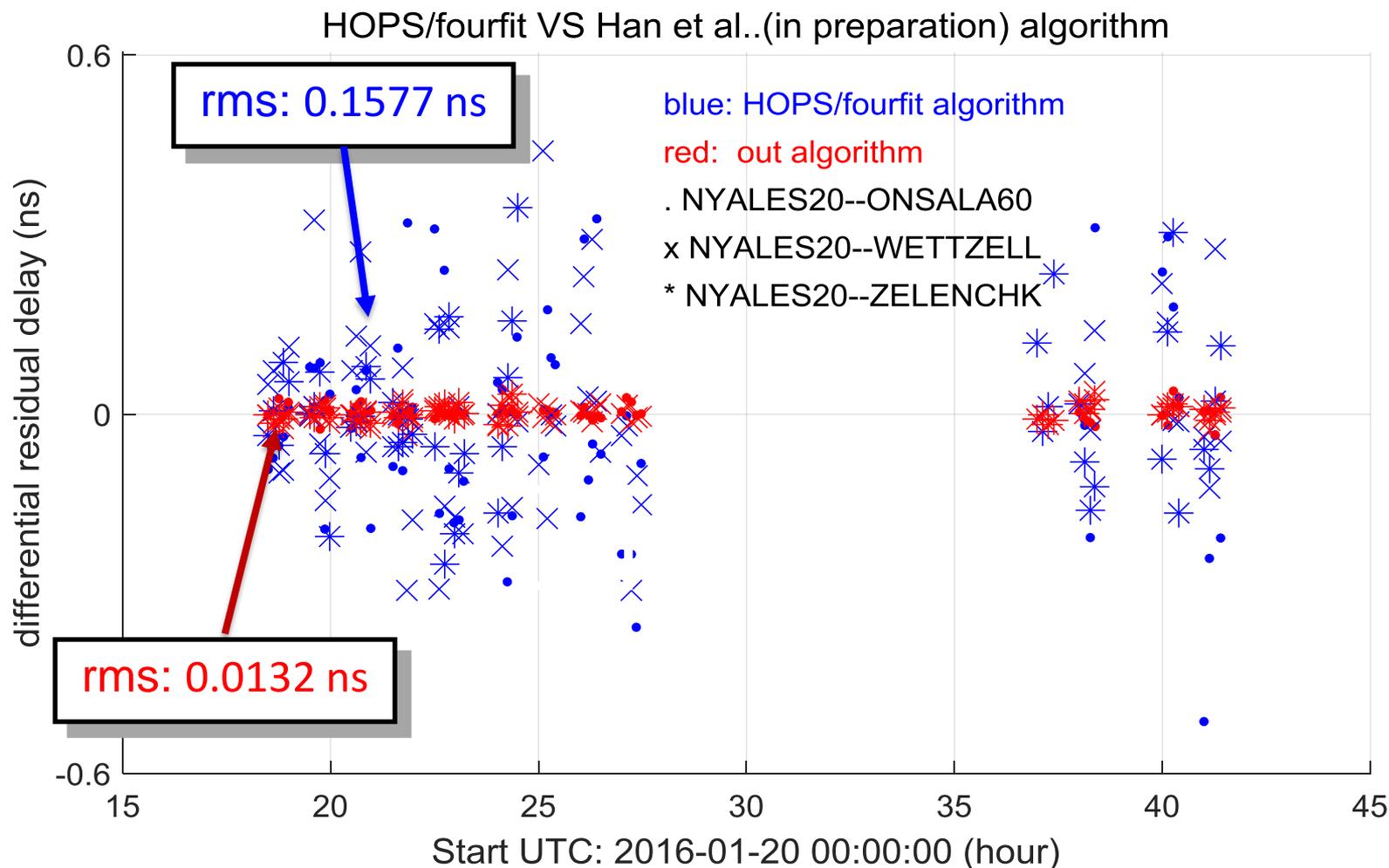
flow chart of our algorithm

- **OCEL(Observing the Chang'E-3 Lander with VLBI)** project has been conducting jointly by IVS and BACC, a global IVS R&D network augmented with two China Deep Space Stations was configured for OCEL.

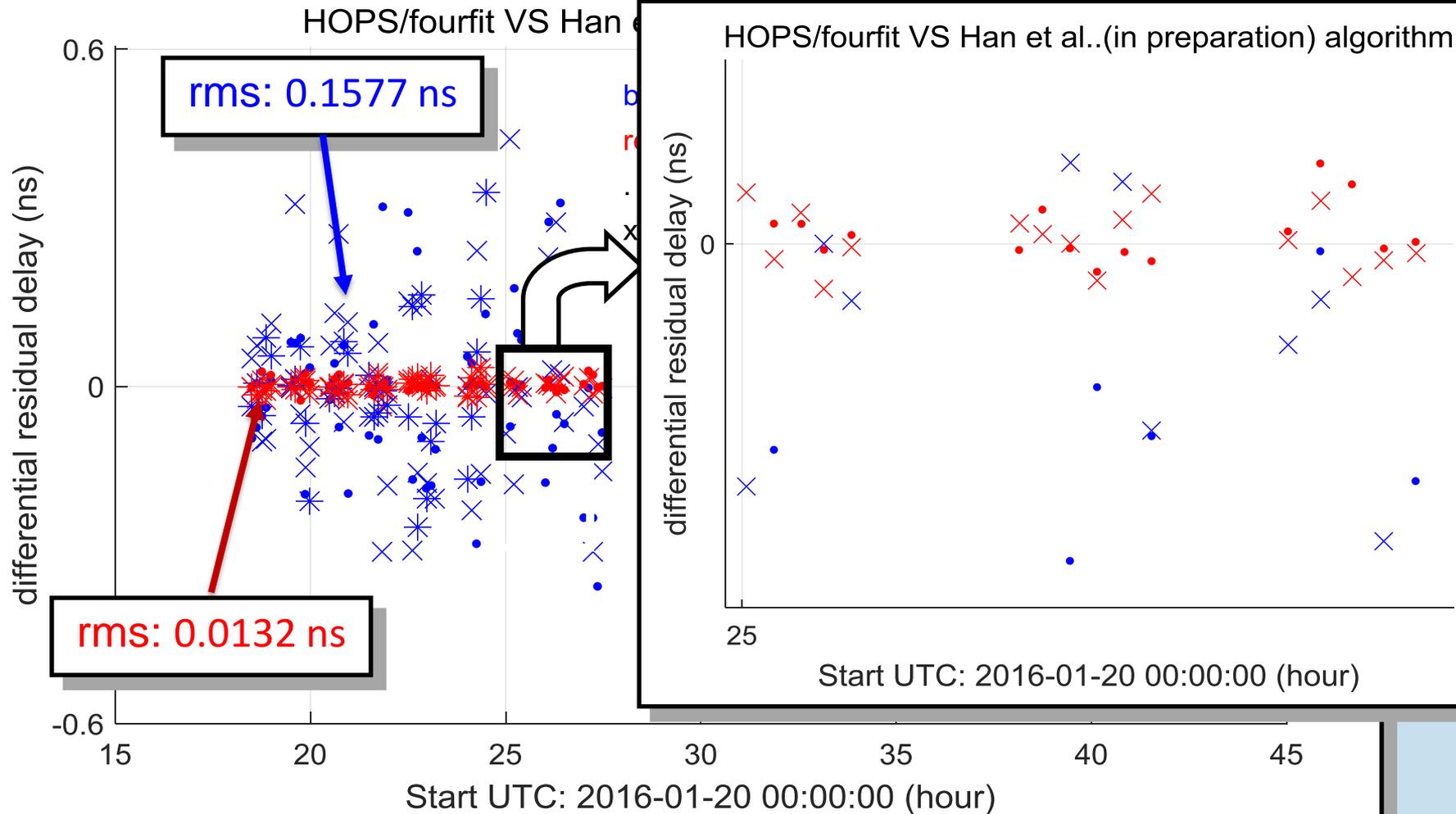


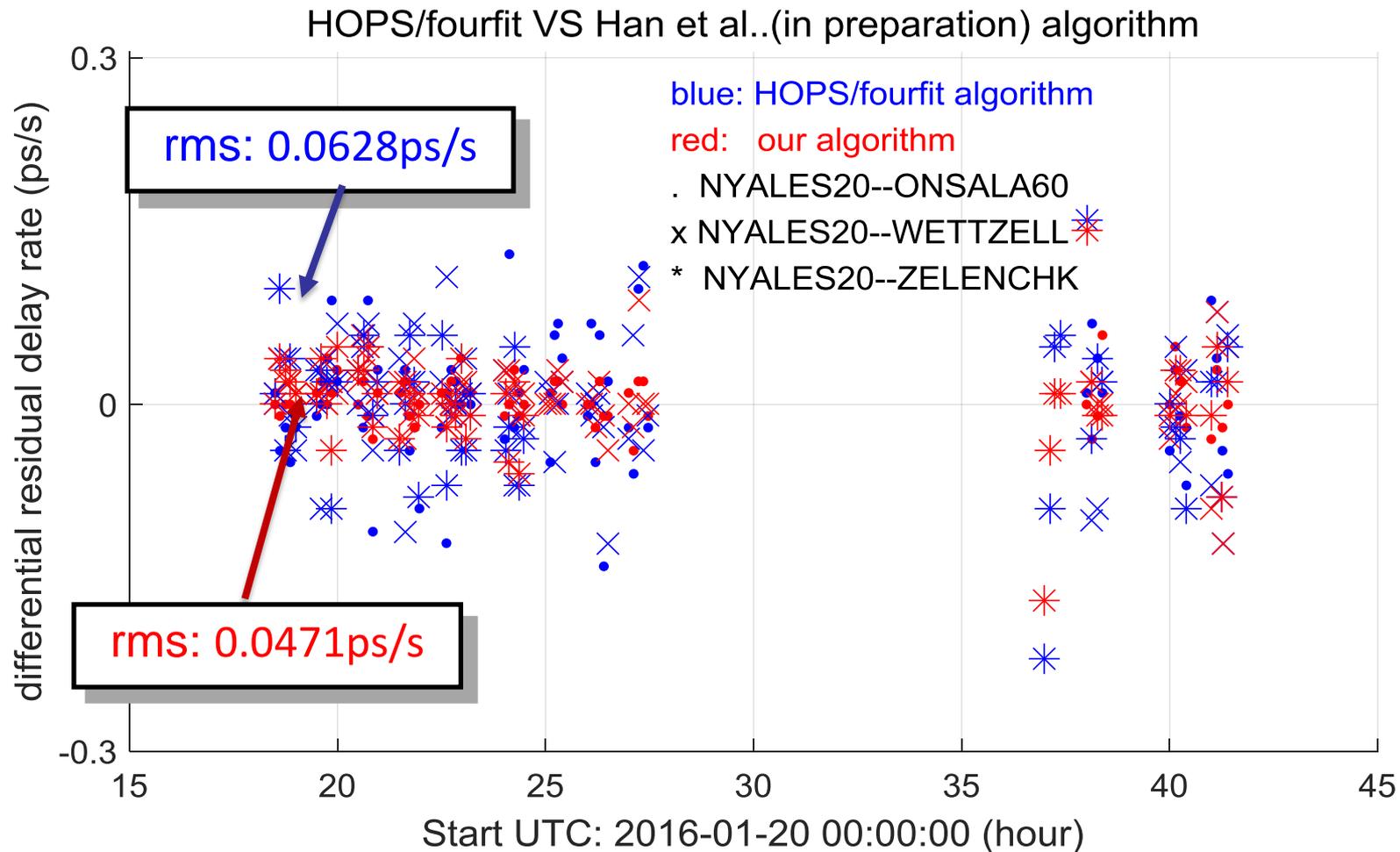
Stations in rd1601

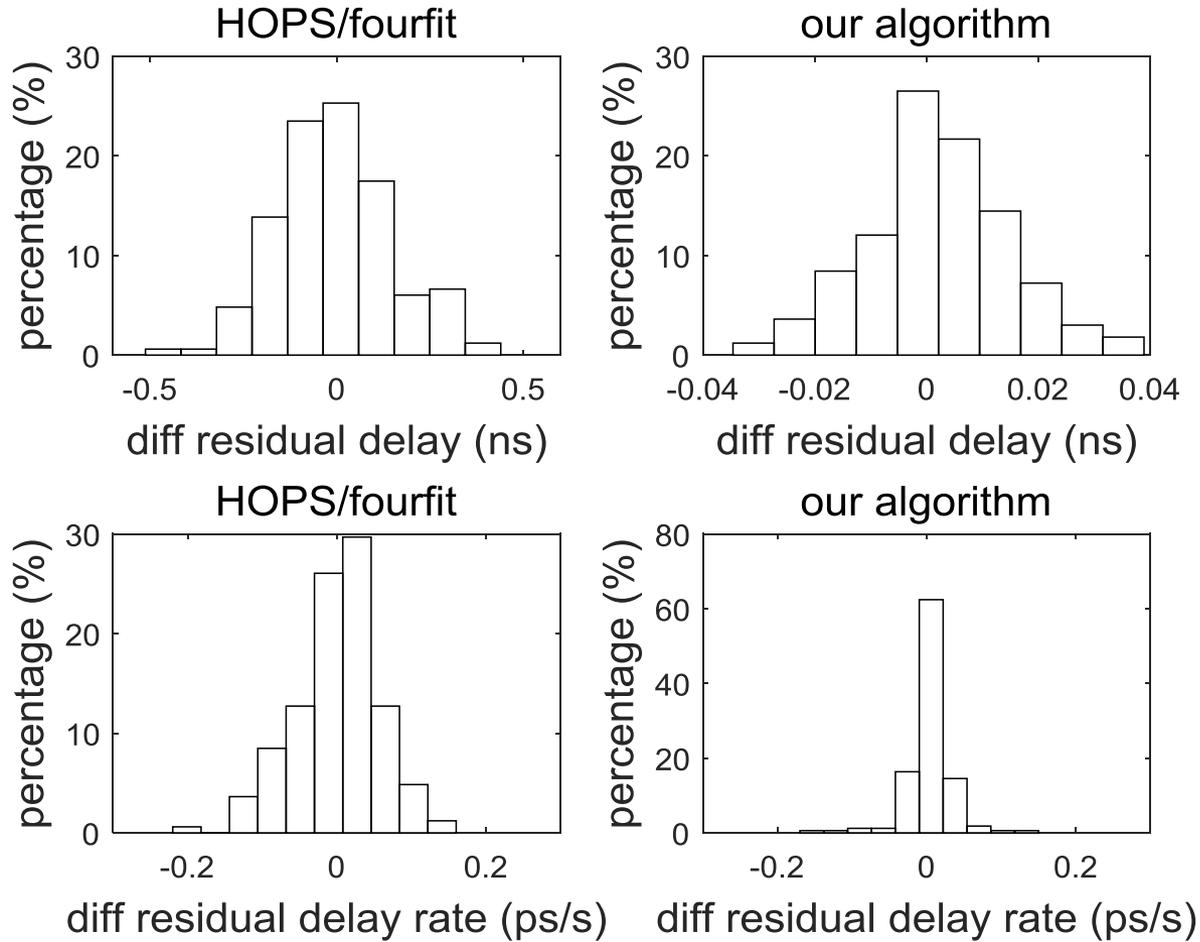
- Results of the algorithm adopted for spacecraft navigation ([Kikuchi,2004](#); [Tang,2012](#)) are deemed as true reference value.



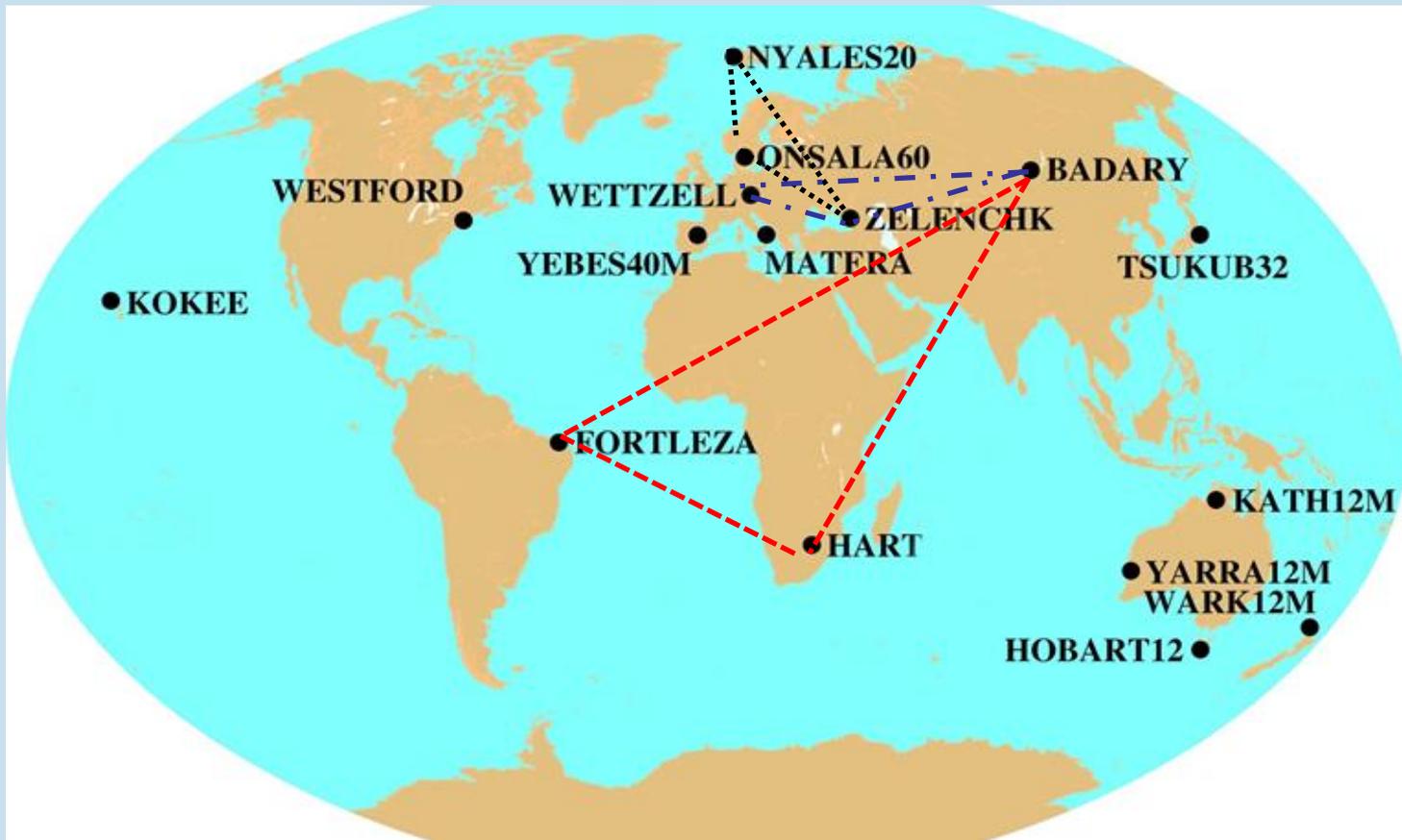
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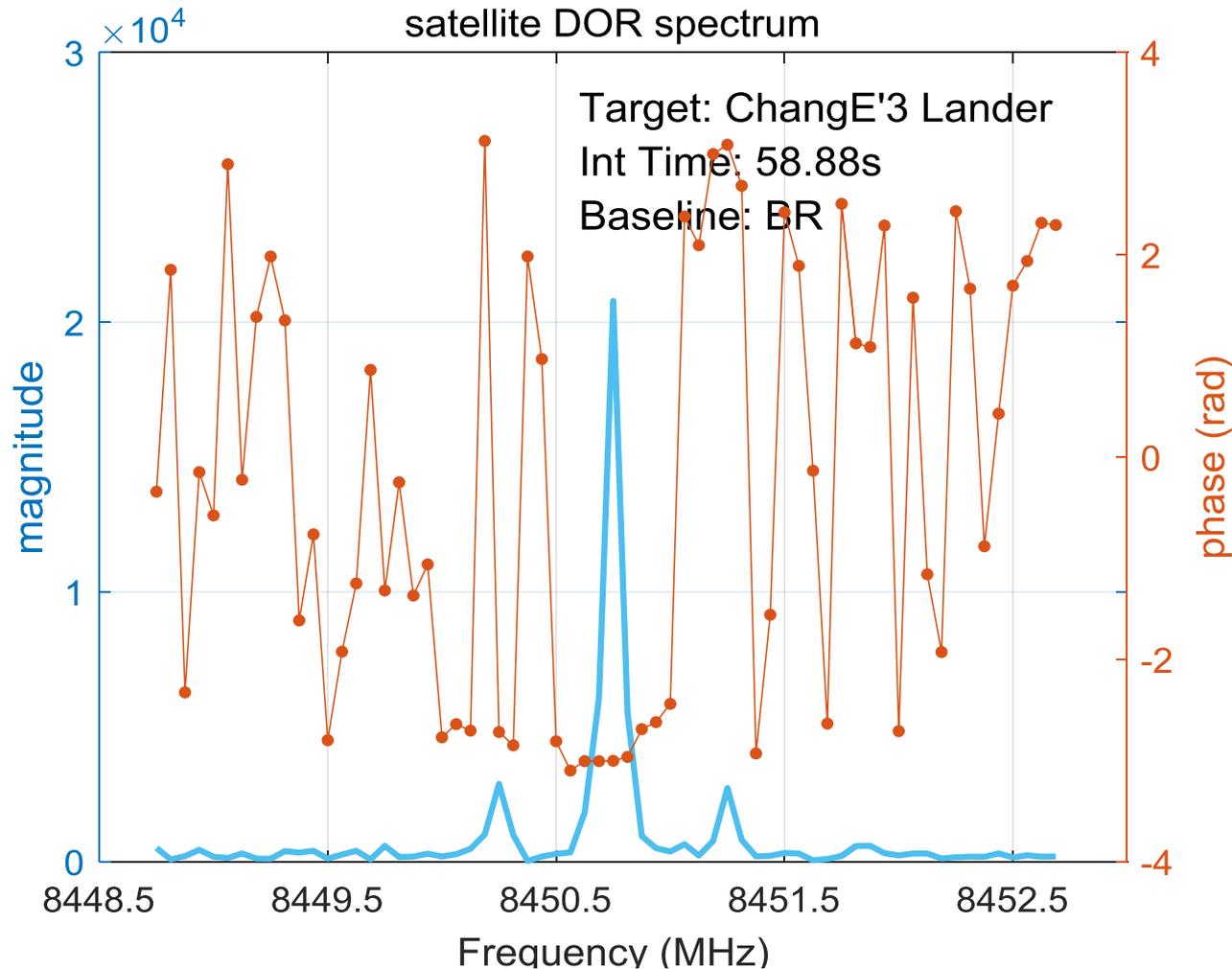


error distribution

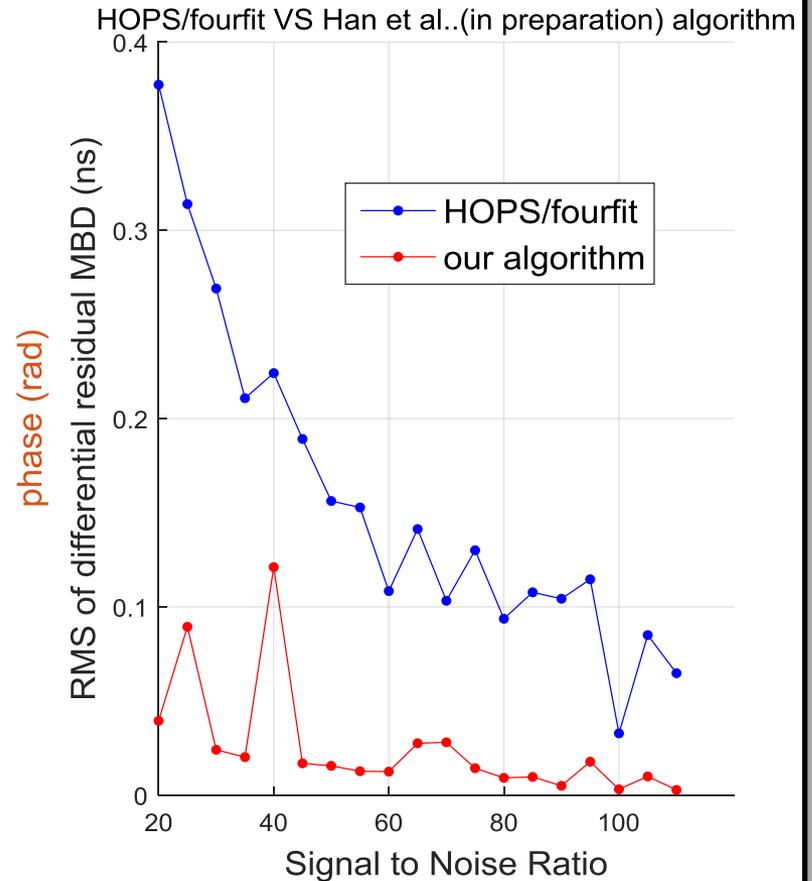
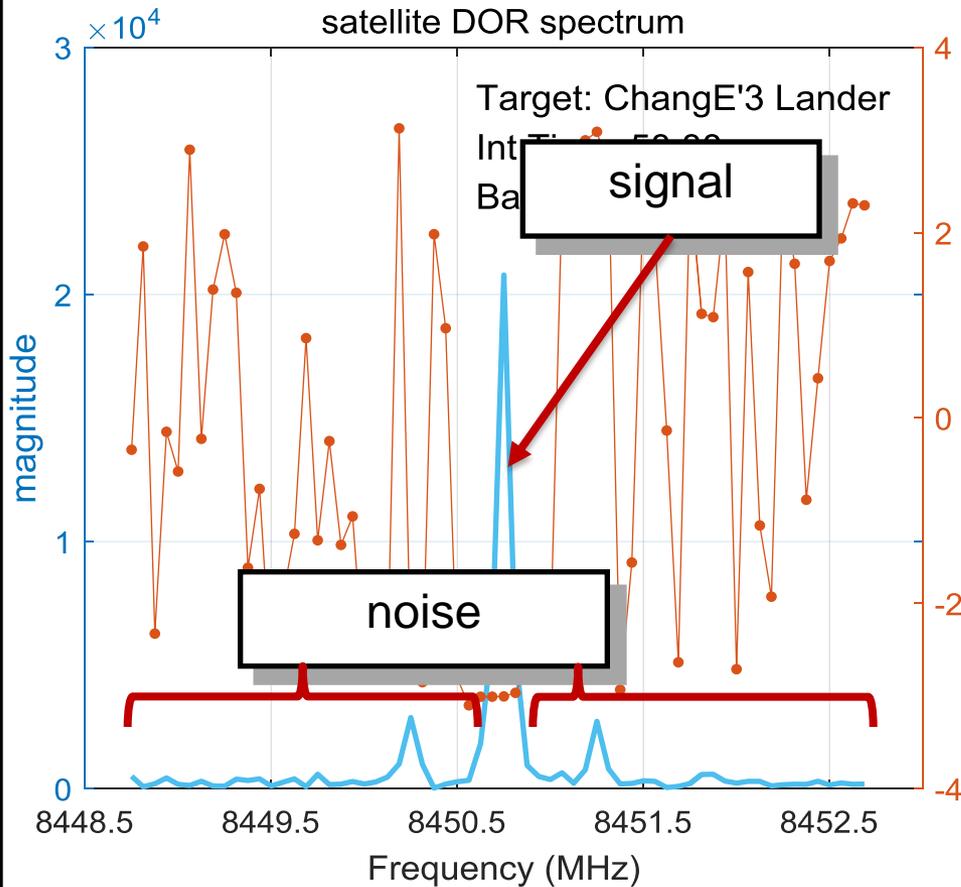


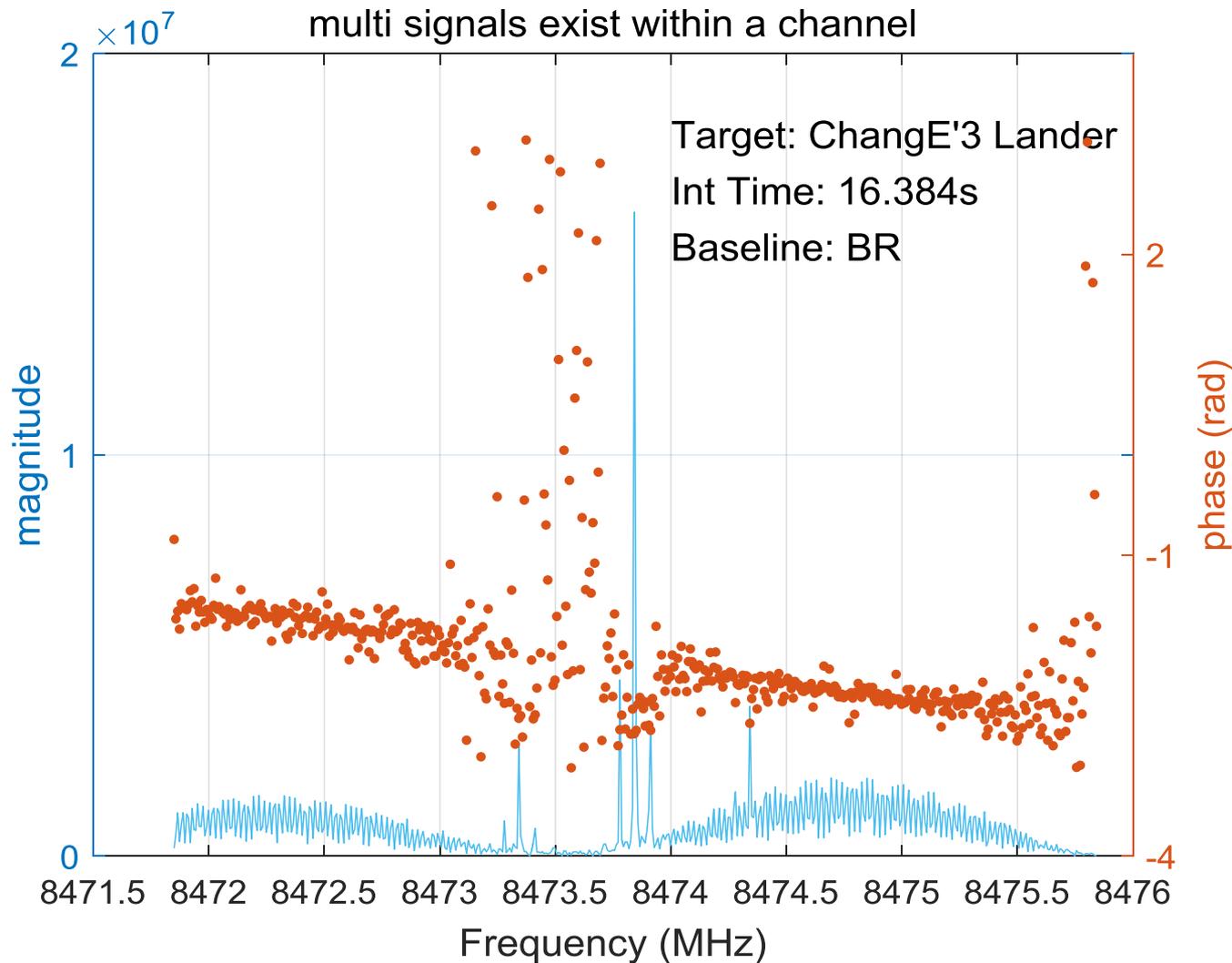
closure delay	Baseline Combination(3 examples..)		
	NY/ON/ZC	BD/FT/HH	BD/WZ/ZC
rms(ns)			
HOPS/fourfit	0.2748	0.4259	0.2598
our algorithm	0.0808	0.1057	0.0928

- Algorithm has better results than original algorithm, **why?**



- Algorithm has better results than original algorithm, **why?**







**Thank you for your attention!**

**Questions are welcomed!**

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